SAM: The Sensitivity of Attribution Methods to Hyperparameters



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Als confused by out-of-distribution examples

Nguyen, Yosinski, Clune. CVPR 2015

Goodfellow et al. 2015 Alcorn et al. CVPR 2019



cheetah 0.99

starfish 0.99

gibbon 0.99

school bus 0.98

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Attribution maps as explanations



Deconvnet: Visualizing and understanding convolutional networks. Zeiler et al. 2014 Guided-backprop: Striving for simplicity: The all convolutional net. Springenberg et al. 2015 Integrated Gradients: Axiomatic Attribution for Deep Networks. Sundararajan et al. 2018 CAM: Learning Deep Features for Discriminative Localization. Zhou et al. 2016 LIME: Why should i trust you?: Explaining the predictions of any classifier. Ribeiro et al. 2016 SmoothGrad: removing noise by adding noise. Smilkov et al. 2017 MP: Interpretable Explanations of Black Boxes by Meaningful Perturbation. Fong et al. 2017 SHAP: A Unified Approach to Interpreting Model Predictions. Lundberg et al. 2017 PDA: Visualizing deep neural network decisions: Prediction difference analysis. Zintgraf et al. 2017 Grad-CAM: Visual Explanations from Deep Networks via Gradient-based Localization, Selvaraju et al. 2017 Grad-CAM++: Improved Visual Explanations for Deep Convolutional Networks. Chattopadhyay et al. 2017 LRP: Beyond saliency: understanding convolutional neural networks from saliency prediction on layer-wise relevance propagation DeepLIFT: Learning important features through propagating activation differences. Shrikumar et al. 2017 RISE: Randomized Input Sampling for Explanation of Black-box Models. Petsiuk et al. 2018 FIDO: Explaining image classifiers by counterfactual generation. Chang et al. 2019 Expected Gradients: Learning Explainable Models Using Attribution Priors. Erion et al. 2019 FG-Vis: Interpretable and Fine-Grained Visual Explanations for Convolutional Neural Networks. Wagner et al. CVPR 2019 Understanding Deep Networks via Extremal Perturbations and Smooth Masks. Fong et al. ICCV 2019 MP-G: Removing input features via a generative model to explain their attributions to classifier's decisions. Agarwal et al. 2020







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0.54 matchstick

Zeiler & Fergus 2014 Ribeiro et al. 2016 Smilkov et al. 2017 Fong & Vedaldi 2017

Are these explanations correct and reliable?

Method 0: Saliency maps

Gradient





Problems:

• too noisy

Method 1: Smoothed saliency maps

Smilkov et al. 2017

Gradient SmoothGrad



$$\frac{1}{n}\sum_{1}^{n}\nabla_{\boldsymbol{x}}f(\boldsymbol{x}+\mathcal{N}(0,\sigma^{2}))$$

Problems:

too noisy



Gradient



GoogLeNet

Gradient



Gradient Gradient

GoogLeNet-R



GoogLeNet



A *robust* classifier i.e. adversarially trained with noisy images







Gradient Gradient



A *robust* classifier i.e. adversarially trained with noisy images

#1.1 Robust models are able to handle the additive noise to the input image



Gradient Gradient



GoogLeNet GoogLeNet-R

" A *robust* classifier i.e.

adversarially trained with noisy images

#2: Smoothed gradients can be misinterpreted

Gradient



GoogLeNet

Gradient



GoogLeNet-R

A *robust* classifier i.e. adversarially trained with noisy images

#2: Smoothed gradients can be misinterpreted



#3: Many attribution maps are sensitive to hyperparams





#3: Many attribution maps are sensitive to hyperparams

Gradient SmoothGrad SP LIME MP



#3: Many attribution maps are sensitive to hyperparams



The booming field of artificial intelligence (AI) is grappling with a replication crisis much like the



Idea: Find a minimal region s.t. when blurred out would minimize classification score

$$\boldsymbol{m}^{*} = \mathop{\arg\min}_{\boldsymbol{m}} \lambda \left\|\boldsymbol{m}\right\|_{1} + f(\operatorname{blur}(\boldsymbol{x},\boldsymbol{m}))$$

Meaningful-Perturbation (MP)

0/200 Index:

Index: 0/200



ResNet

ResNet-R

Meaningful-Perturbation (MP)



Input image $N_{iter}=10$ $N_{iter}=150$ $N_{iter}=300$ $N_{iter}=450$

SSIM: 0.9313

(b) Sensitivity to changes in the number of iterations N_{iter}

Meaningful-Perturbation (MP)



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#5 Pixel-wise sensitivity translates to sensitivity in accuracy scores/downstream tasks





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#6: Some hyperparameters are more detrimental



Conclusions



- 1. Gradient images for robust classifiers are smooth
- 2. Smoothing gradients may cause misinterpretation
- 3. Many attribution methods are sensitive to hyper-parameters
- 4. For robust classifiers, attribution maps are more robust

